Report type writing- everything here will be saved, however, also will all be exported to latex-which will be backed up and referenced.

Design Chapter:

The design of the container was a process that encompassed several months. This chapter will go through the entire mechanical design process, outlining the key aims, decisions and analysis behind the container design.

During the mechanical design process, there were two different software’s used: OpenSCAD and SOLIDWORKS. OpenSCAD is an open source software which is compatible with all major computer operating systems. This enabled the start of the design process to occur before the beginning of the Michaelmas Term. Furthermore, as mentioned in the introduction, using opensource software is a key tenant of this project as it needs to be replicable for teams worldwide. SOLIDWORKS however, is not open source, but was still used. This is because there is some key functionality in SOLIDWORKS which helps reduces the time needed on a few of the important steps (such as rendering photos, heat simulations and producing engineering drawings). However, as I will lay out further in the chapter, the main designs were completed on OpenSCAD, and they do hold enough information for a group elsewhere to replicate without significant difficulty.

A key consideration was what processes would be needed for the manufacturing of the container. The engineering department has different facilities which could be useful including: a workshop with a CNC machine, multiple different 3D printers, a mechanical workshop which I would be able to use along with an electrical workshop. These all were considered when designing the container and each will be mentioned during this chapter.

The first stage of the design process was to outline a specification for the testing container. These specifications were drawn from the project brief, the literature review and discussion with one of my supervisors Professor Moritz Riede. The specification of the design is outlined below:

1. The container must be able to accommodate a 30 mm x 30 mm substrate provided by AFMD research group
2. The container must be leakproof to outside air
3. The container must allow electrical connections from outside to connect to the substrate for measurements.
4. The container must enable the substrate to be heated to a given temperature\*.
5. The container must have a window allowing light to be shone into the box
6. The container must contain a gas inlet.
7. The container should fit into the small glovebox inlet with diameter 150 mm.

This specification is a clear guide to what functionality there needs to be within the container, as well as any size limitations. As mentioned in both the introduction and literature review, is is essential for the container to be leakproof, to ensure that the solar cell does not degrade due to atmospheric O2 and water vapour. This would result in flawed results due to the cell having some unmeasured degradation before the experiments even begin. Another important point in the specification is the ability of the cell to be heated to a given temperature\*. This functionality is important as its role is to attempt to emulate a lifetime (20 years) of temperature degradation in the space of 3 months.

The gas inlet is another feature to enhance the degradation. This will be used to create a ‘cocktail’ of different gases (guided by the literature) to try and emulate lifetime degradation of the solar cell. The last point on the specification is to ensure the ease of use with the AFMD research group. The gloveboxes they use have a small inlet with a diameter of 150 mm, using this would vastly reduce the time needed to insert the solar cell into the testing container.

Along with the specification, some further goals were drawn up to provide aims that would provide important functionality but were not essential for the solar cell. These are shown below:

1. Build a Python based GUI (graphical user interface) to enable programmatic testing of the solar cell
2. Enable a programmable atmosphere for the box which should be embedded into the GUI built.

These goals are important to ensure the ease of use of the box, as well as to reduce the amount of time needed for setting up and running the container. The programmatic testing of the cell, along with a programable atmosphere is useful as it enables the researchers to simply input time, temperature and what combination of gases, which then allows the system to run a test, all the time measuring the outputs and logging it for further analysis.

This specification provided the structure for the testing container. Using work done in the literature review, it was clear that this type of testing container is unusual for the market, thereby requiring innovative design. I was put in contact with Karl-Augustin Zaininger - a Physics researcher who had developed a simplified version of this device – to discuss viable methods for achieving the specifications. This conversation allowed me to create an extremely simple first iteration of the design shown in figure (n).

This model was 3D printed to provide a physical representation (with a photo shown in figure (n)), where it became possible to see some of the flaws that were hidden by the virtual design. The first thing was that this design was very small, making it difficult for use within the glovebox. This was a problem as all assembly needed to occur within a glovebox to ensure there would be no unwanted oxygen or water residue able to degrade the cell. Adding to this, it seemed that there wouldn’t be enough room to wire the components in the container, this would cause significant problems as the modularity of the design would be compromised. This would go against one of the tenants of the project (modularity) which would be a problem when thinking of using this set up on different substrate layouts.

These problems caused a redesign of the container, resulting in the model shown in figure (n). The box is larger in this with dimensions x\*y\*z, with a wall thickness w, resulting in more space within the container as well as a more robust device. This part is the outer shell, with a subsequent substrate holder supposed to be held inside the outer shell. The substrate holder was designed specifically to go with this particular substrate layout, resulting in a more detailed design. The substrate layout was provided to me by Dr. Grey Christophoro, a researcher working in the Physics department, and can be shown in figure (n). As can be seen in figure (n) the substrate has x contact points and y cells, meaning that the substrate holder is required to also have room to provide a means to contact to the electrical contact points, without hindering the flow of air around the cell, or the light incident on the cell surface. The solution was to develop s small lid which would be screwed into the substrate holder. This lid was designed so that the outline did not block any light being incident on the cells. The lid outline can be seen in figure n.

Another important consideration was the ability for the substrate holder to be easily attached to the outer shell within the glovebox. Therefore, the substrate holder needs to have electrical wiring within it, to ensure the connections that it made to the cells, could be moved away to another part which can be easily ‘plugged-in’ to another component. This idea